

Stochastic models for the space-time evolution of martensitic avalanches

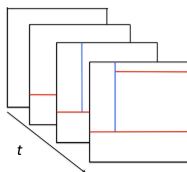
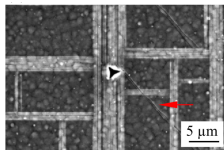
Pierluigi Cesana

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Kyushu University, Japan

Hysteresis, Avalanches and Interfaces in Solid Phase Transformations
20th September, 2016

Overview

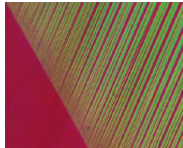
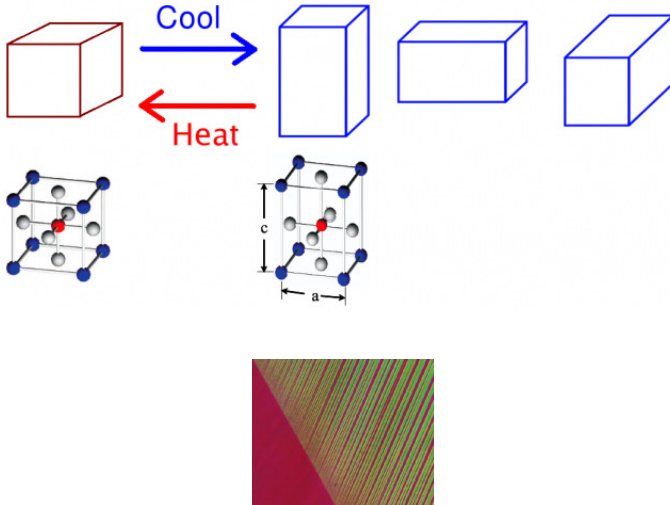
- General Branching Random Walk model for martensitic avalanches
- Fragmentation model (SOC à-la-Bak) for the crystal variants of an elastic crystal



Niemann et al. APL Mater. 4, 064101 (2016)

- Joint work with John Ball and Ben Hambly (Oxford)
 - J. Ball, P.C., B. Hambly, Proceedings ESOMAT15
 - P.C., B. Hambly, in progress
 - P.C., M. Porta, T. Lookman, JMPS 2014
 - S. Patching, P.C, A. Rueland, in preparation

Martensitic transformation



Aus-Mar interface, C.Chu

Elasticity framework

- $F \in \mathbb{R}^{3 \times 3}$ the deformation gradient
- $\psi(F)$ the free-energy density

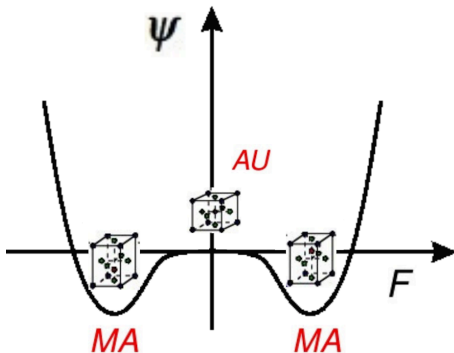
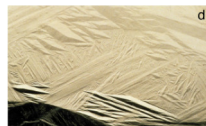
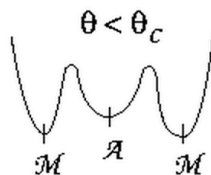
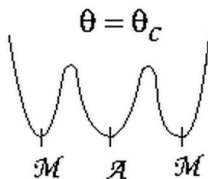
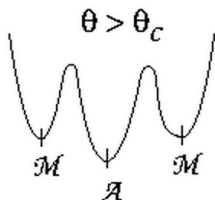


Figure : First-order phase transition, fixed temperature

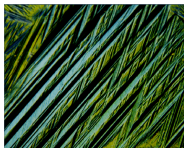
Effect of temperature

- $F \in \mathbb{R}^{3 \times 3}$ the deformation gradient
- $\psi(\theta; F)$ the free-energy density

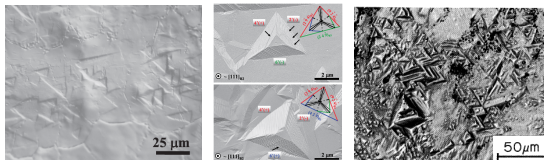


Courtesy Tim Duerig

Self-similarity



Transformed sample of Cu-Zn-Al (after cooling). Optical microscope with polarized light 3mm x 2mm (Morin)



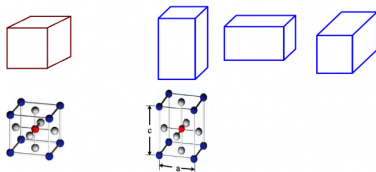
LEFT-CENTER: SEM micrograph pictures, Ti-Ni;
RIGHT: Ti-Ni-Cu (orthorhombic martensite), self-acc.

M. Nishida et al. (2012) Self-accommodation of B19 martensite in Ti-Ni shape memory alloys-Part 1. Morphological and crystallographic studies of the variant selection rule, Philosophical Magazine, 92:17, 2215-2233.

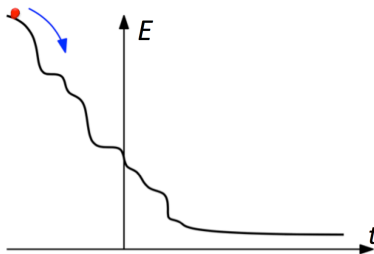
Martensitic transformation

*A martensitic transformation is a phase transition which involves a cooperative motion of a set of atoms across an interface causing a **shape change** and a **sound**.*

Philip C. Clapp, ICOMAT95



Avalanches

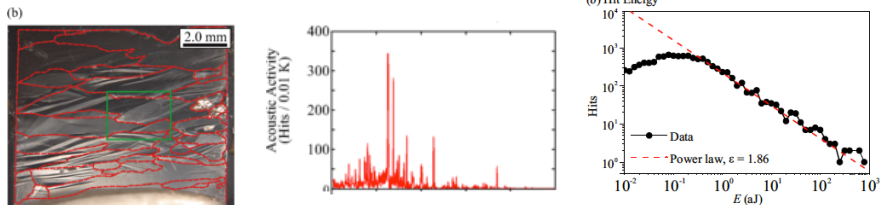


- intermittent evolution as a sequence of jerks (avalanches)
- athermal behavior
- jerky behavior is consequence of **disorder**



Acoustic emissions

- Avalanches detected by ultrasonic AEs



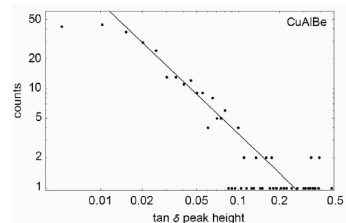
- 1) Polarized light optical micrograph of sample of martensitic NiMnGa at room temperature.
- 2) Emission hits per 0.01K temperature interval (acoustic activity).
- 3) Histogram of the number of hits vs the absolute energy.

Niemann et al. (2014), PRB

Universality

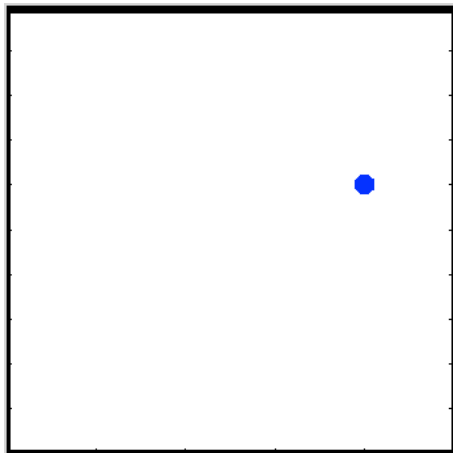
Universality class critical exponents α and ϵ and variant-multiplicity for systems transforming from cubic to selected martensitic symmetries. They are estimated as averaged values in the adiabatic limit. For monoclinic martensites, data reported for Cu–Al–Zn, Cu–Al–Be, Cu–Al–Mn [23] and Ni–Al [24] have been used. For orthorhombic martensite data are from two Cu–Al–Ni [23] and from a Cu–Al–Mn alloy [17]. For tetragonal martensite data from single- and poly-crystalline Fe–Pd have been used [27].

M-symmetry	α	ϵ	Multiplicity
Monoclinic	3.0 ± 0.2	2.0 ± 0.2	12
Orthorhombic	2.4 ± 0.1	—	6
Tetragonal	2.0 ± 0.3	1.6 ± 0.1	3

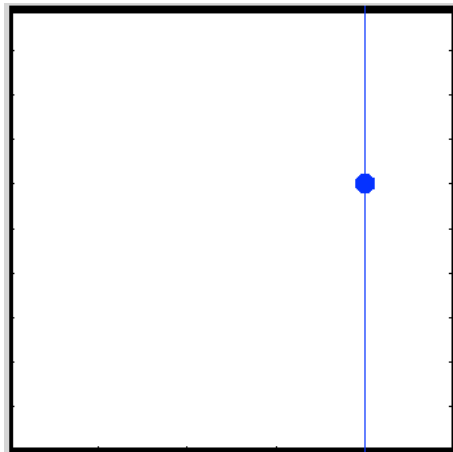


- A. Planes et al. (2013) *Acoustic emission in martensitic transformations*, Journal of Alloys and Compounds, 577S S699-S704
- E. Salje et al. (2009) *Jerky elasticity: Avalanches and the martensitic transition in shape-memory alloys*, APL 95

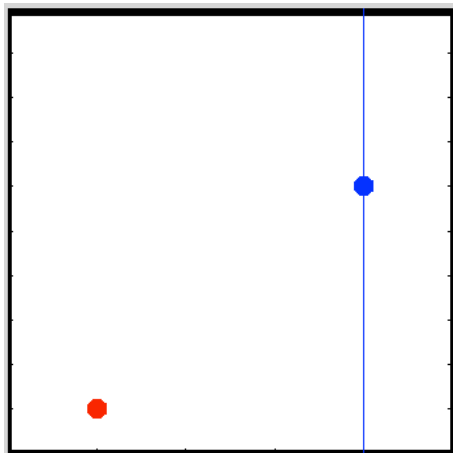
Fragmentation



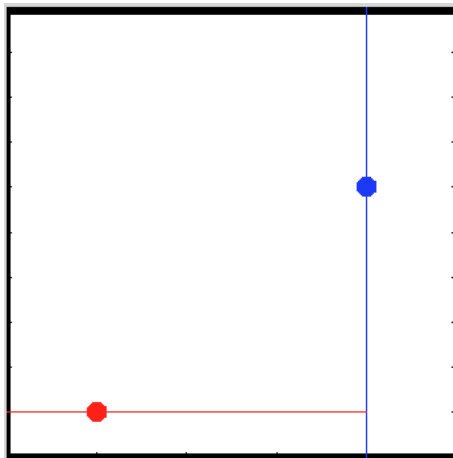
Fragmentation



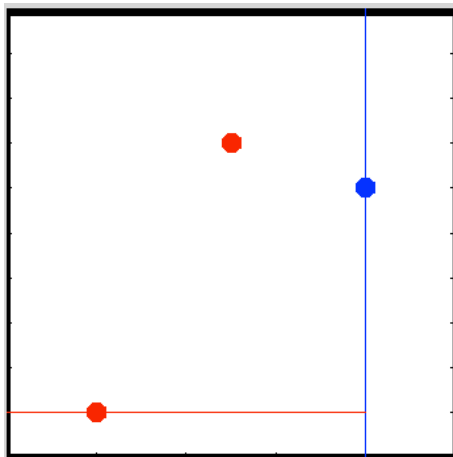
Fragmentation



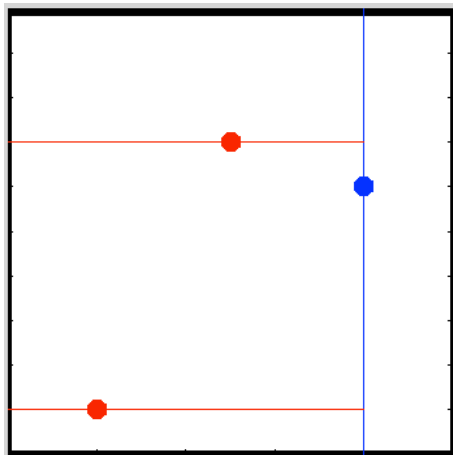
Fragmentation



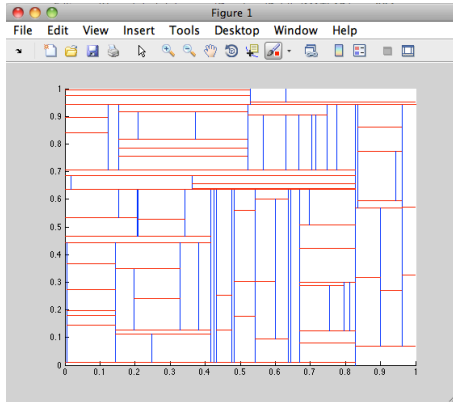
Fragmentation



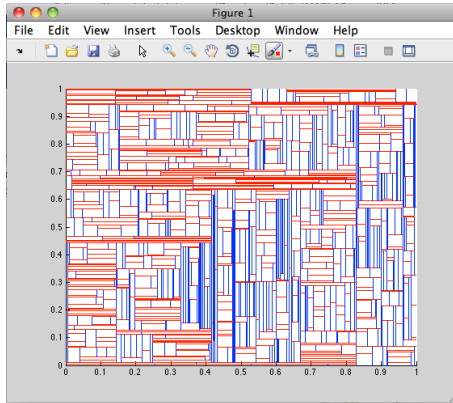
Fragmentation



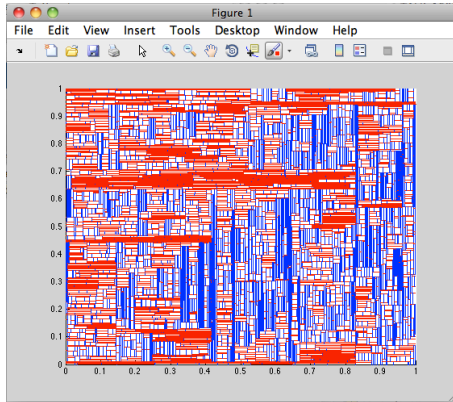
$n=100$



$n=1000$

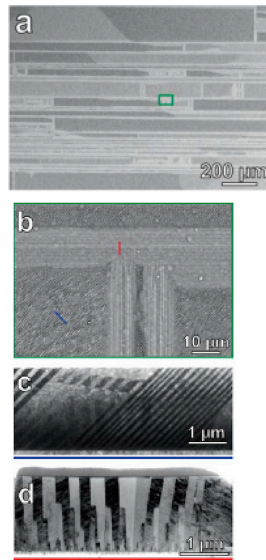


$n=5000$

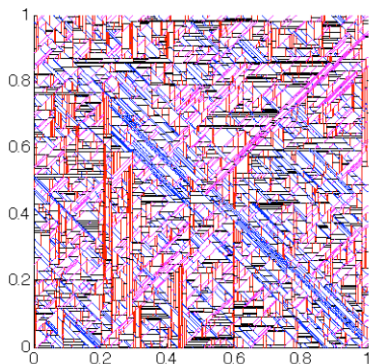
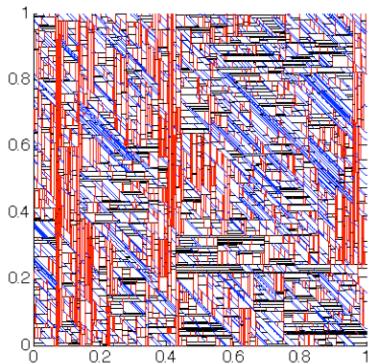


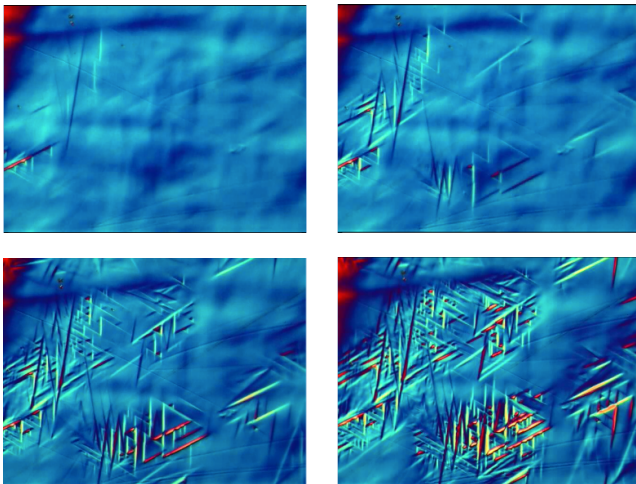
SEM micrograph (backscattered electron contrast) of an epitaxial Ni-Mn-Ga film in the martensitic state at room temperature. (b) A zoom-in shows two different microstructures. All contrast comes from mesoscopic twin boundaries. (c, d) TEM micrographs at cross-sections along the lines marked in (b).

R. Niemann et al. (2014) PRB



3, 4 Phases





Avalanche formation of a habit plane variant cluster with triangular morphology in TiNbAl [Kamioka, ..., T. Inamura, Proceedings of ESOMAT 2015]

6 Phases

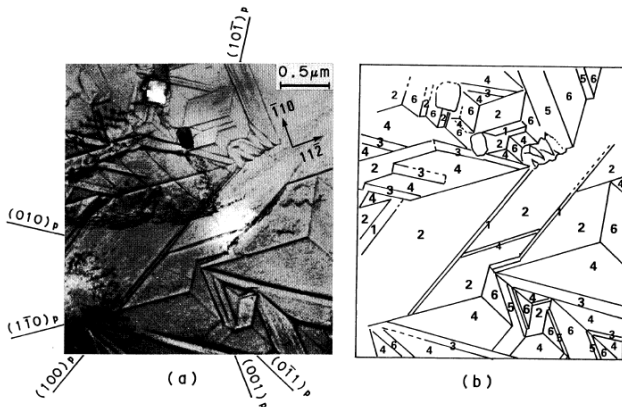
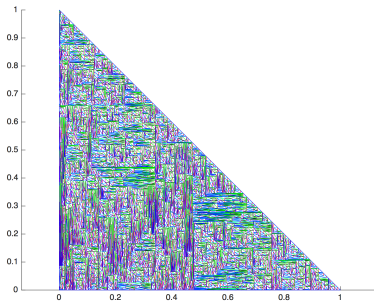
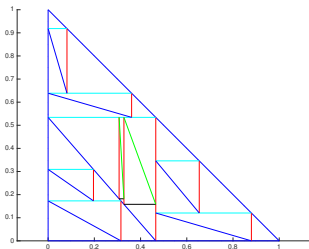


Fig. 9 (a) Configuration of six variants. Surface marking on the surface of the parent phase (electron micrograph).
(b) Schematic explanation of (a).

Self-accommodation structure in Ti-Ni-Cu Orthorhombic Martensite, Watanabe et al., J. Japan Inst. Metals, 54, N.8 1990.

Other shapes



The fragmentation model

- Pick a point at random (nucleation)

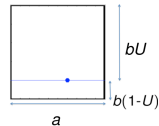
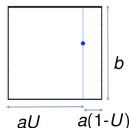


- Choose a direction, V (with probability p) or H



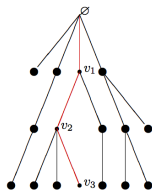
- The general rectangle (a, b) splits into

$$(a, b) \rightarrow \begin{cases} (aU, b), (a(1-U), b) \text{ with probability } p \\ (a, bU), (a, b(1-U)) \text{ with probability } 1-p \end{cases}$$



General Branching Random Walk

- The whole structure can be captured in a tree as the evolution inside any rectangle does not affect what happens outside that rectangle.



- Thus in our tree each vertex will represent a rectangle .
- We use some results from Biggins¹: super-critical GBRW have a shape theorem indicating the region where the number of particles will grow exponentially.

¹How fast does a general branching random walk spread? *IMA Vol. Math. Appl.*, 84, Springer, New York, 1997.

– log transformation

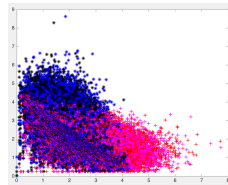
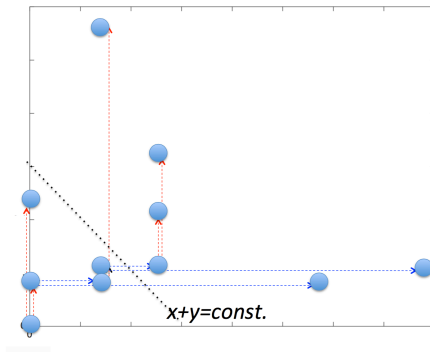
- Transformation:

$$x = -\log a \geq 0$$

$$y = -\log b \geq 0$$

- Each rectangle is an individual in the branching process and location is determined by its sides $\rightarrow$ GBRW in $\mathbb{R}_+^2$.
- Ancestor $(0, 1) \times (0, 1) \rightarrow (0, 0)$
- The smaller the rectangles, the larger the coordinates

Constructing the tree

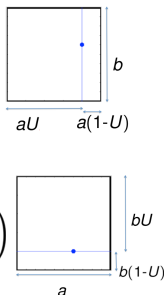


Branching Random Walk

- In Crump-Mode-Jagers (General Branching Process) model an individual z :
 - is born at time $\sigma_z \geq 0$,
 - has a lifetime $L_z \geq 0$,
 - has offspring whose birth times are determined by a point process ξ_z on $(0, \infty)$.
- For a General Branching Random Walk we include a point process for the birth position η_z (as well as birth times).

General Branching Random Walk

- Let the Bernoulli r.v. $B_i = \begin{cases} 0 & \text{horizontal} \\ 1 & \text{vertical} \end{cases}$ $1-p$
- Let U_i uniform r.v. in $[0, 1]$
- Outcomes of the general rectangle (a, b) are

$$(a, b) \rightarrow \begin{cases} (B_i U_i a, (1 - B_i) U_i b) \\ (B_i (1 - U_i) a, (1 - B_i) (1 - U_i) b) \end{cases}$$


General Branching Random Walk

- Birth time: proportional to $-\log(\text{Area})$ of rectangle splitting
- $(\eta_i, \xi_i) = \text{space, time position of offspring of } i$

$$\eta_i, \xi_i = \begin{cases} (-B_i \log U_i, -(1 - B_i) \log U_i) & -\log U_i \\ (-B_i \log(1 - U_i), -(1 - B_i) \log(1 - U_i)) & -\log(1 - U_i) \end{cases}$$

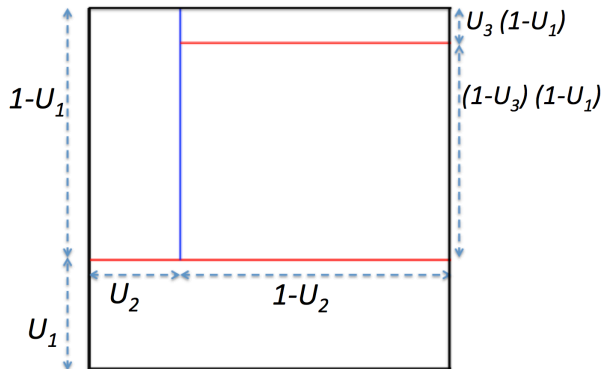
- The space-time point process:

$$(\eta(d\mathbf{x}), \xi(dt)) = \begin{cases} (\delta_{(-\log u, 0)}(d\mathbf{x}), \delta_{-\log t}(dt)) I_{\{u=t\}} + \\ (\delta_{(-\log(1-u), 0)}(d\mathbf{x}), \delta_{-\log(1-t)}(dt)) I_{\{u=t\}} & 1/2 \\ (\delta_{(0, -\log u)}(d\mathbf{x}), \delta_{-\log t}(dt)) I_{\{u=t\}} + \\ (\delta_{(0, -\log(1-u))}(d\mathbf{x}), \delta_{-\log(1-t)}(dt)) I_{\{u=t\}} & 1/2 \end{cases}$$

- birth time of $\sigma_\emptyset = 0$
- birth time of $\sigma_{ij} = \sigma_i + \inf\{t : \xi_i(t) \geq j\}$

Time

- $t = -\log(1 - U_1) - \log(1 - U_2) - \log(1 - U_3)$
- Largest area is $(1 - U_1)(1 - U_2)(1 - U_3)$
- That is $t = -\log(\text{Area})$
- at time t largest area is e^{-t}



Shape Theorem

- We want to keep track of $N_t(A) = \#$ individuals in the set A at time t .

Take $A \subset \mathbb{R}_+^2$ closed, convex, non-empty interior.

- ① If $A \cap \{(x, y) : x + y = 1\} = \emptyset$ then

$$t^{-1} \log N_t(tA) \rightarrow -\infty \quad t \rightarrow \infty, \text{ a.s.}$$

- ② If $A \cap \{(x, y) : x + y = 1\} \neq \emptyset$ then

$$t^{-1} \log N_t(tA) \rightarrow \beta \geq 0 \quad t \rightarrow \infty, \text{ a.s.}$$

where

- $\beta = \sup\{\alpha^*(a) : a \in A\}$
- $\alpha^*(\mathbf{a}) = \inf_{\mathbf{w}}\{\mathbf{a} \cdot \mathbf{w} + \alpha(\mathbf{w})\}$
- $\alpha(\mathbf{a}) = \inf\{\phi : m(\mathbf{w}, \phi) \leq 1\}$
-

$$m(\mathbf{w}, \phi) = E \int e^{-\mathbf{w} \cdot \mathbf{x} - \phi t} \eta_{\emptyset}(d\mathbf{x}) \xi_{\emptyset}(dt), \quad \mathbf{w} \in \mathbb{R}^2, \phi \in \mathbb{R}_+.$$

the moment-generating function for the position and birth times of offsprings.

Interpretation

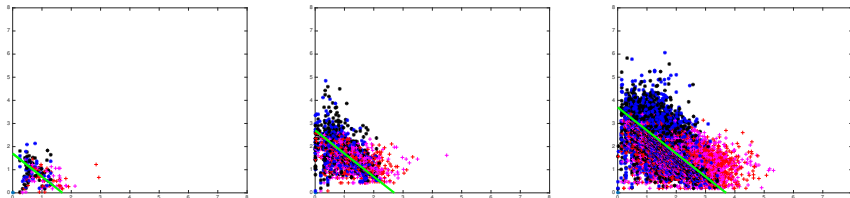


Figure : $n = 10^2, 10^3, 10^4$

The line $x + y = t$
Areas $\sim e^{-t}$

Application

- At time t largest Area $= e^{-t} \rightarrow t = -\log \text{Area}$
- Shape theorem describes exponential growth of individuals N in a certain set $A \subset \mathbb{R}_{++}^2$

$$\lim_{t \rightarrow \infty} t^{-1} \log(t N_t(A)) = \beta \geq 0$$

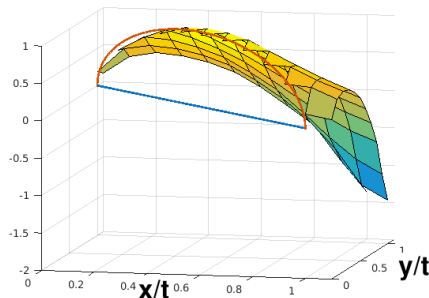
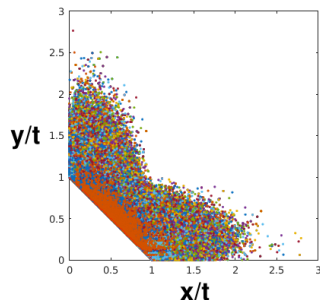
- for finite t , approximation formula

$$N_t(A_{x,y}) = e^{t f(\frac{x}{t}, \frac{y}{t})}$$

with:

$$f\left(\frac{x}{t}, \frac{y}{t}\right) = \begin{cases} \sqrt{1 - (2p - 1)^2} \sqrt{1 - \left(\frac{x}{t} - \frac{y}{t}\right)^2} + \\ \quad + (1 - 2p)\left(\frac{x}{t} - \frac{y}{t}\right) & \text{if } \frac{x}{t} + \frac{y}{t} = 1 \\ -\infty & \text{if } \frac{x}{t} + \frac{y}{t} \neq 1 \end{cases}$$

Numerical results (rectangles)

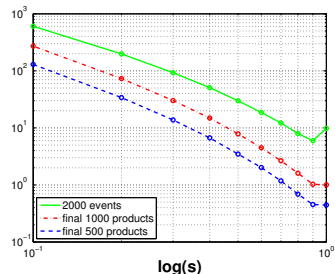
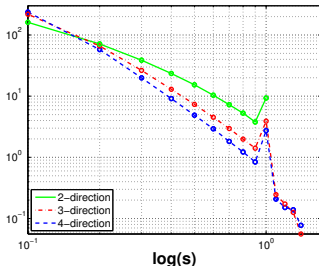


- for $p = \frac{1}{2}$, $n = 2000$, $t \approx 6.9$
- Analytical solution

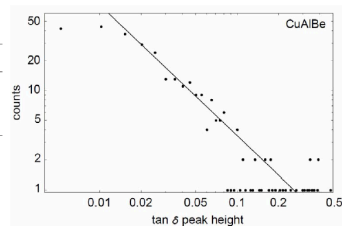
$$f\left(\frac{x}{t}, 1 - \frac{x}{t}\right) = 2\sqrt{\frac{x}{t}\left(1 - \frac{x}{t}\right)}$$

holds on the line $\frac{x}{t} + \frac{y}{t} = 1$ ($ab = e^{-t}$)

Numerical results (interfaces)



M -symmetry	α	ϵ	Multiplicity
Monoclinic	3.0 ± 0.2	2.0 ± 0.2	12
Orthorhombic	2.4 ± 0.1	—	6
Tetragonal	2.0 ± 0.3	1.6 ± 0.1	3



Salje et al. (2009) *Jerky elasticity: Avalanches and the martensitic transition in shape-memory alloy*, APL 95

Case with bias

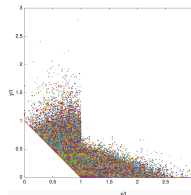
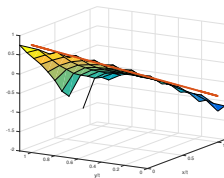


Figure : Histograms, $p = 0.1$

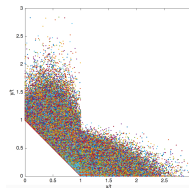
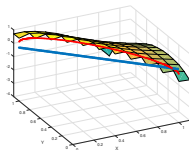
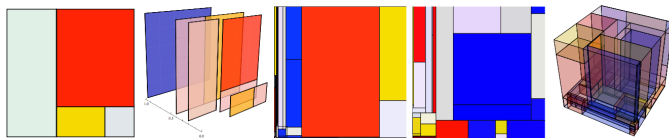


Figure : Histograms, $p = 0.3$

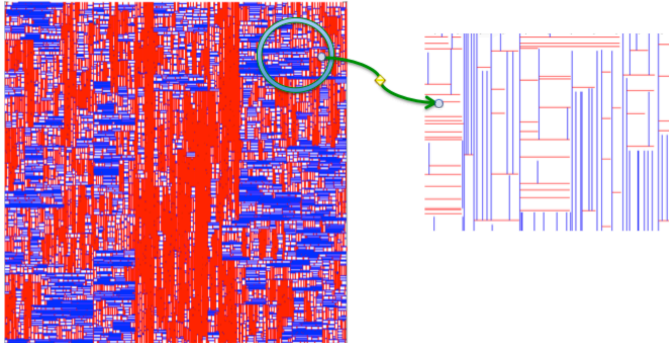
Mondrian process

The Mondrian Process, D. M. Roy, Y. W. Teh, Advances in Neural Information Processing Systems 21 (NIPS 2008)

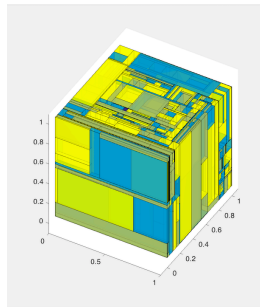
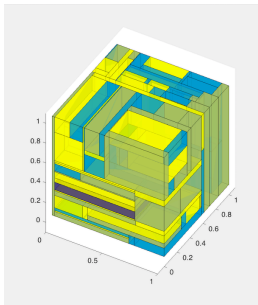
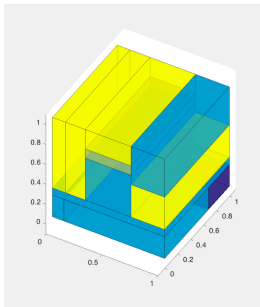


- Initial budget $\lambda > 0$
- Nucleus picked at random
- Cut is made with probability proportional to its length
- Cost of cut $\propto$ its length
- Arrest when the total length reaches the budget

Fractal microstructure

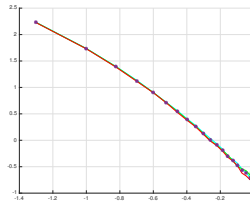
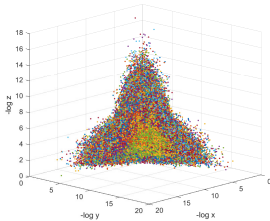


3D model



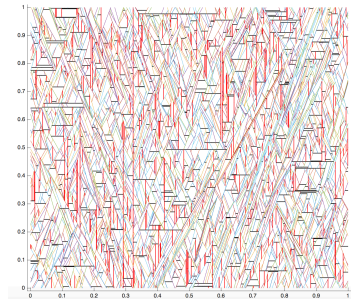
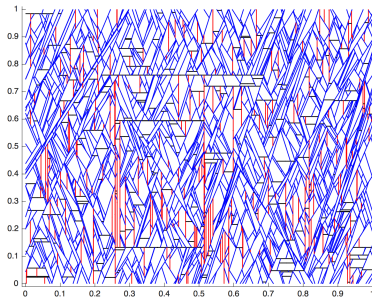
$n = 10, 10^2, 10^3$ events.

3D model



Cloud and plate distribution.

Random angles

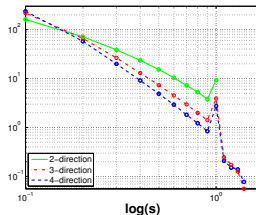
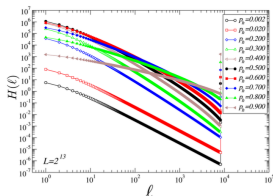


- Surface energy
- Unpinning strategy (joint w. A. Collevocchio, Monash)

TIVP model

G. Torrents et al., Geometrical model for martensitic phase transitions: understanding criticality and weak universality during microstructure growth, to appear

- discrete model
- our focus on new individuals
- discrete features



- statistics for interfaces and areas

Self-similar nested microstructure

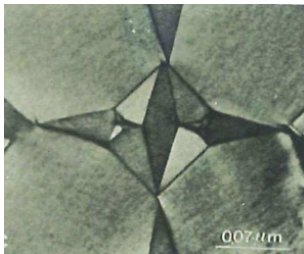


Figure : Star disclination in $\text{Pb}_3(\text{VO}_4)_2$ (*HREM*), C. Manolikas, S. Amelinckx, Phys. Stat. Sol. 1980.

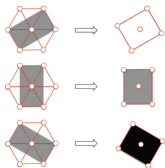
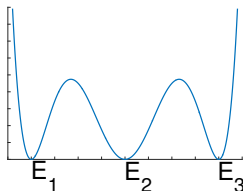


Figure : The 2D version of the hexagonal-to-orthorhombic transformation (Mg-Cd , $\text{Mg}_2\text{Al}_4\text{Si}_5\text{O}_{18}$) is the triangle-to-centered-rectangle (TR) transformation.

Exact solutions

$$\bullet \Psi(F) \leftarrow \min_{F \in \mathbb{R}^{3 \times 3}} + \textit{Kinematic Compatibility}$$

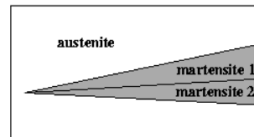
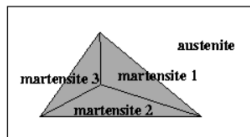
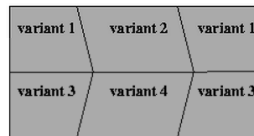
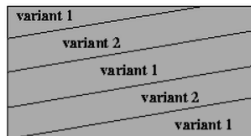
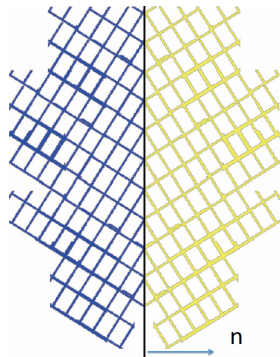


- To find a deformation field $y : \Omega \rightarrow \mathbb{R}^3$ s.t.

$$\nabla y \in \{E_1, E_2, E_3\}$$

and y is Hölder continuous.

Kinematic compatibility (KC)

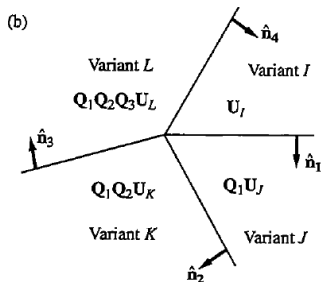
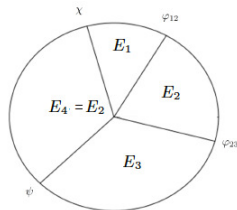


$$F_1 = \nabla y_1 \quad F_2 = \nabla y_2$$

Conservation of tangential component of $\nabla y_1, \nabla y_2 \rightarrow F_1 - F_2 = a \otimes n$

Kinematic compatibility

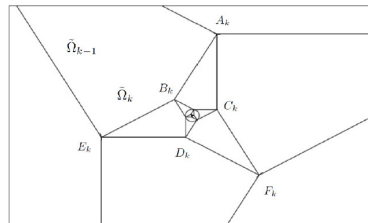
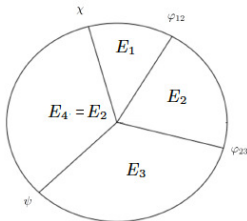
$$y : \Omega \rightarrow \mathbb{R}^3 : \nabla y \in \{E_1, E_2, E_3\}$$



1. $Q_1 U_I - U_I = \mathbf{b}_1 \otimes \hat{\mathbf{n}}_1$
2. $Q_1 Q_2 U_K - Q_1 U_I = \mathbf{b}_2 \otimes \hat{\mathbf{n}}_2$
3. $Q_1 Q_2 Q_3 U_L - Q_1 Q_2 U_K = \mathbf{b}_3 \otimes \hat{\mathbf{n}}_3$
4. $U_I - Q_1 Q_2 Q_3 U_L = \mathbf{b}_4 \otimes \hat{\mathbf{n}}_4$
5. $\hat{\mathbf{n}}_1, \hat{\mathbf{n}}_2, \hat{\mathbf{n}}_3$ and $\hat{\mathbf{n}}_4$ lie on a plane

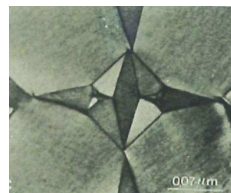
Parallelogram Martensite Microstructure

Star-clination



→ Rigidity: solution is unique

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